

Maulana Abul Kalam Azad University of Technology, West Bengal
(Formerly West Bengal University of Technology)
SYLLABUS FOR BACHELOR OF TECHNOLOGY IN MECHANICAL ENGINEERING
(Effective from academic session 2018-19)

Subject Code : PC-ME 503	Category: Professional Core Courses
Subject Name : Kinematics and Theory of Machines	Semester : Fifth
L-T-P : 3-1-0	Credit: 4
Pre-Requisites: Engineering Mechanics	

Course Objectives:

1. To understand the kinematics and rigid- body dynamics of kinematically driven machine components
2. To understand the motion of linked mechanisms in terms of the displacement, velocity and acceleration at any point in a rigid link
3. To be able to design some linkage mechanisms and cam systems to generate specified output motion
4. To understand the kinematics of gear trains

Course Contents:

Module No.	Description of Topic	Contact Hrs.
1	Classification of mechanisms- Basic kinematic concepts and definitions- Degree of freedom, mobility- Grashof's law, Kinematic inversions of four bar chain and slider crank chains. Limit positions- Mechanical advantage- Transmission angle- Description of some common mechanisms- Quick return mechanism, straight line generators- Universal Joint- Rocker mechanisms.	6
2	Displacement, velocity and acceleration analysis of simple mechanisms, graphical velocity analysis using instantaneous centers, velocity and acceleration analysis using loop closure equations- kinematic analysis of simple mechanisms- slider crank mechanism dynamics- Coincident points- Corioli's component of acceleration- introduction to linkage synthesis- three position graphical synthesis for motion and path generation.	7
3	Classification of cams and followers- Terminology and definitions- Displacement diagrams- Uniform velocity, parabolic, simple harmonic and cycloidal motions- derivatives of follower motions- specified contour cams- circular and tangent cams- pressure angle and undercutting, sizing of cams, graphical and analytical disc cam profile synthesis for roller and flat face followers.	5
4	Involute and cycloidal gear profiles, gear parameters, fundamental law of gearing and conjugate action, spur gear contact ratio and interference/undercutting- helical, bevel, worm, rack & pinion	6

	gears, epicyclic and regular gear train kinematics.	
5	Surface contacts- sliding and rolling friction- friction drives- bearings and lubrication, Friction clutches- Belt and Rope drives- Friction in brakes.	6
6	Vibrations- Free and forced vibration of undamped and damped Single DOF systems, Resonance, Transmissibility Ratio, Effect of damping, Vibration Isolation, Critical Speed of Shafts.	6
7	Balancing of Reciprocating and Rotating Masses- Static balancing, Unbalance of force or moment, Dynamic balancing of rotating masses- graphical and analytical methods; Swaying couple; Hammer blow.	4
8	Governors- Use and classification; Study and analysis of Porter, Proell and Wilson-Hartnell governors; Sensitiveness, stability, isochronism, hunting, effort and power of governors.	3
9	Flywheel- Inertia force and inertia torque in reciprocating engine, correction couple (torque), Turning moment diagram and flywheel design.	3
10	Gyroscope- Gyroscopic couple and precessional motion, Effect of gyroscopic couple on aeroplane and ship, Stability of two wheel and four wheel vehicles taking turn.	2

Course Outcomes:

After completing this course, the students can design various types of linkage mechanisms for obtaining specific motion and analyze them for optimal functioning

Learning Resources:

1. T. Bevan, Theory of Machines, 3rd Edition, CBS Publishers & Distributors, 2005.
2. A. Shariff, Theory of Machines, Dhanpat Rai Publication, New Delhi, 2000.
3. W.L. Cleghorn, Mechanisms of Machines, Oxford University Press, 2005.
4. R.L. Norton, Kinematics and Dynamics of Machinery, 1st Edition, McGraw Hill India, 2010.
5. A. Ghosh and A.K. Mallick, Theory of Mechanisms and Machines, Affiliated East-West Pvt. Ltd., New Delhi, 1988.